

Here is an excellent comparison of TK and FORTRAN. The example is obtained from the following textbook: *Introduction to Computing* by James, Smith and Wolford; Harper-Collins.

To build a better mouse trap, the value of spring stiffness (k) is to be determined from the following equation:

$$\frac{T_c + \theta_1 \cdot k}{T_c + \theta_2 \cdot k} = \cos \left[\sqrt{\frac{t \cdot k}{l_0}} \right]$$

You will quickly realize that this formula cannot be easily solved using your calculator or spreadsheet. A typical FORTRAN program is given in the textbook as shown below:

```
C REAL ROOT BY SEARCHING WITH CONVERGENCE BY NEWTON-RAPHSON
  REAL K,KN,KN1
  WRITE (6,2)
  2  FORMAT ('1','ROOT DETERMINATION BY SEARCH WITH CONVERGENCE BY')
  WRITE (6,20)
  20  FORMAT (' ',15X,'NEWTON-RAPHSON METHOD'//)
  READ (5,3) DELK, EPSI
  3  FORMAT (2F10.0)
  K=0.2
  FOFK=(0.625+0.3*K)/(0.625+3.27*K)-COS(SQRT(K/0.0006)*.191)
  4  KN=K+DELK
  FOFKN=(0.625+0.3*KN)/(0.625+3.27*KN)-COS(SQRT(KN/0.0006)*.191)
  IF (FOFK*FOFKN) 8,5,7
  5  WRITE (6,6) KN, FOFKN
  6  FORMAT (' NEW SPRING CONSTANT = ',F5.3, 'LB-FT/RAD FOFKN =') +, F6.4
  STOP
  7  K = KN
  FOFK = FOFKN
  GO TO 4
  8  FOFKN = (0.625+0.3*KN)/(0.625+3.27*KN)-COS(SQRT(KN/0.0006)*.0191)
  A = ((.625+3.27*KN)*.30-(.625+.30*KN)*3.27/(.625+3.27*KN)**2
  B = 0.191/(2 * .0006) * SQRT (0.0006/KN) * SIN (SQRT (KN/ .0006) * .0191)
  DFOFKN = A + B
  KN1 = KN - FOFKN/DFOFKN
  IF (ABS (KN1 - KN) - EPSI) 10, 10, 9
  9  KN = KN1
  GO TO 8
  10 FOFKN1 = (0.625+0.3*KN1)/(.625+3.27*KN1)-COS(SQRT(KN1/.0006)*.0191)
  WRITE (6,11) KN1, FOFKN1
  11 FORMAT (' NEW SPRING CONSTANT = ',F5.3, 'LB-FT/RAD FOFKN1 =' +, F6.4
  STOP
  END
```

ROOT DETERMINATION BY SEARCHING WITH CONVERGENCE BY NEWTON-RAPHSON METHOD
 NEW SPRING CONSTANT = 3.362 LB - FT/RAD FOFKN1 = -.0000

Happiness the TK Solver Way!

The TK Solver program to solve the same problem fits on one line! TK Solver does the “Book keeping” and automatically lists all the variables on a separate work sheet.

Rule
$(T_c + \theta_1 \cdot k)/(T_c + \theta_2 \cdot k) = \cos(\text{sqrt}(t \cdot k/l_0))$